

# General Formulation

Finite elements: Dr Colin Cotter

# General formulation

- Fluid dynamics application normally start from differential equations
- Structural mechanics also use point of view of energy of force balance at equilibrium

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Two approaches to formulating problems:

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- Method of weighted residuals

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- Principle of virtual work

# Finite representation

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- The choice of the **conditions** which are to be satisfied defines the type of numerical method.
- The method of weighted residuals illustrates how the choice of different weight (or test) functions in an integral or **weak form** of the equation can be used to construct many of the common numerical methods

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When we have the exact answer which satisfies then  $R(u) = 0$ . This is the only way of ensuring  $R(u)$  is zero everywhere.

# Method of weighted residuals

For a given numerical approximation we don't know the exact form of the residual and so we want to eliminate this term.

We multiply the equation by a weight (test) function, and integrated over the solution region, to obtain

$$\int_{\Omega} w(x) R(u^{\delta}(x)) dx = \int_{\Omega} w(x) L(u(x)^{\delta}) dx - \int_{\Omega} w(x) q(x) dx.$$



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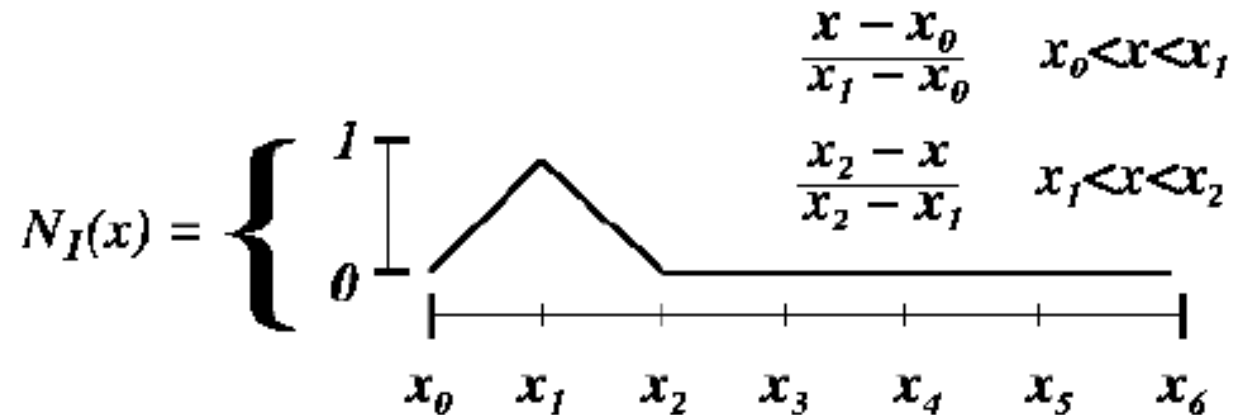
This is the integral (weak) form of the equation, if true for all  $w$

# Finite Elements

If we represent our solution as  $u(x) = \sum_{i=1}^N \hat{u}_i N_i(x)$

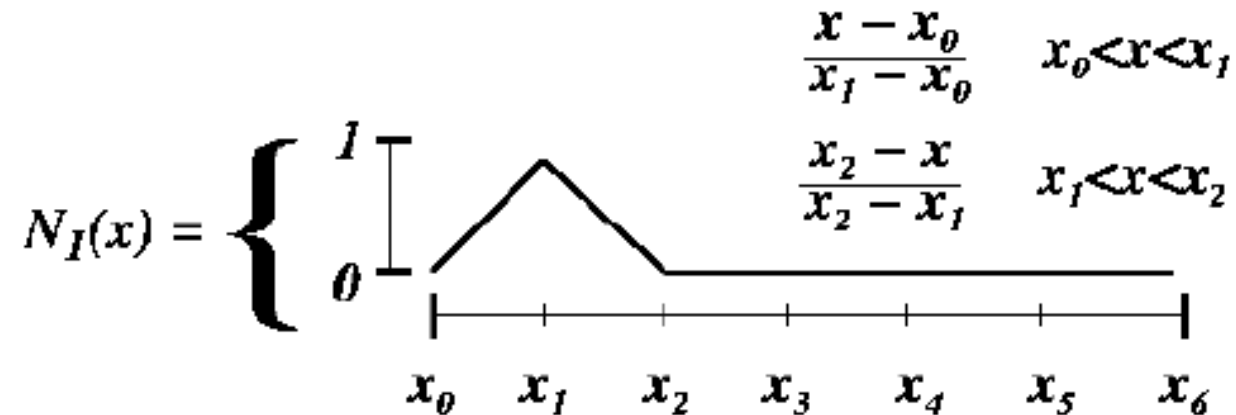
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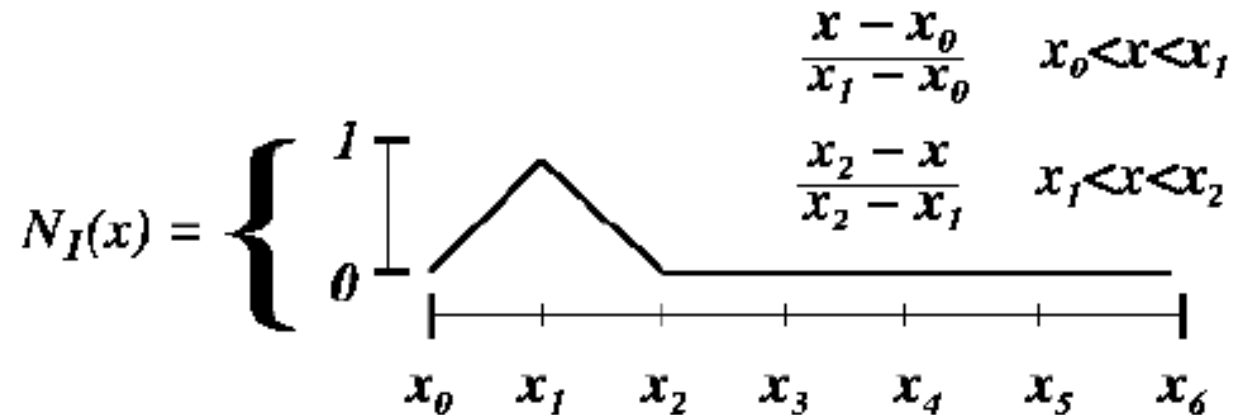
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If we use a different choice of a continuous function so then the projection is referred to as the Petrov-Galerkin methods.

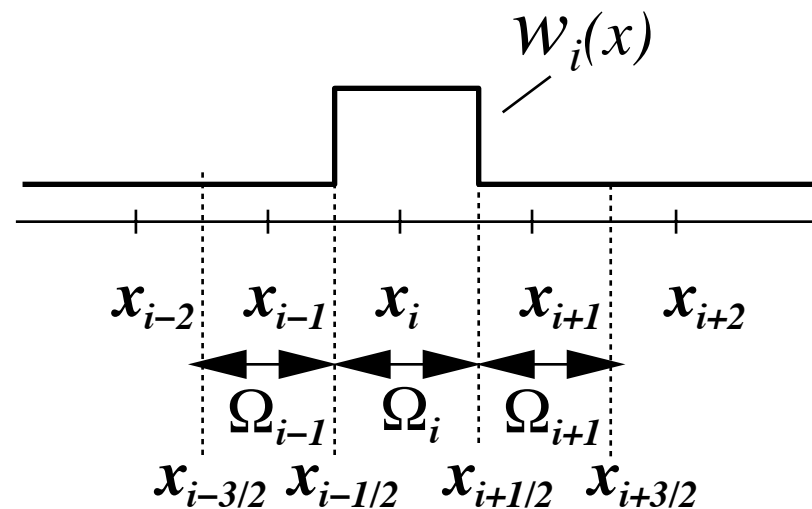
This arises when we want to introduce upwinding into the finite element method

# Finite volume and finite difference

If we choose a step type function which has a value of 1 in a cell and is zero outside then we have a subdomain projection which is used in the finite volume methods.

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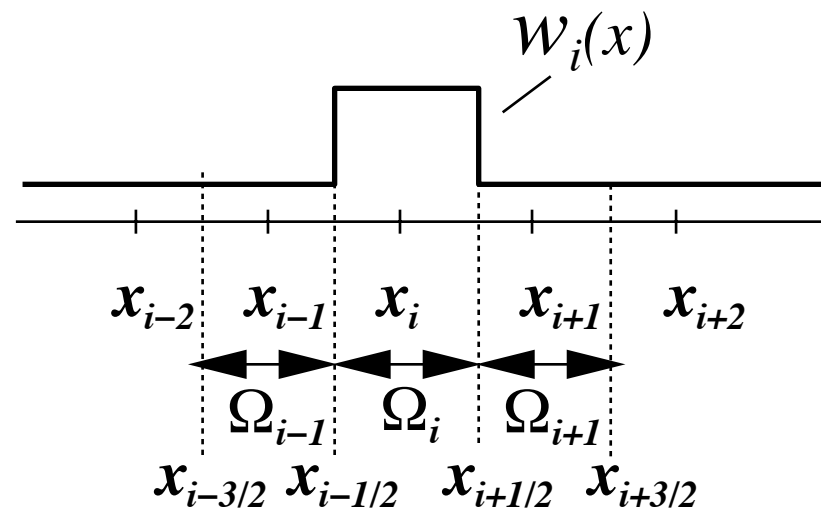
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If we choose  $w_i(x) = \delta(x - x_j)$  where  $x_j$  are the mesh points then we have the collocation method which is the starting point of the finite difference method.

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Then the PDE is classified according to

$$(b^2 - 4ac) > 0 \quad \Rightarrow \quad \textbf{Hyberbolic}$$

$$(b^2 - 4ac) = 0 \quad \Rightarrow \quad \textbf{Parabolic}$$

$$(b^2 - 4ac) < 0 \quad \Rightarrow \quad \textbf{Elliptic}$$

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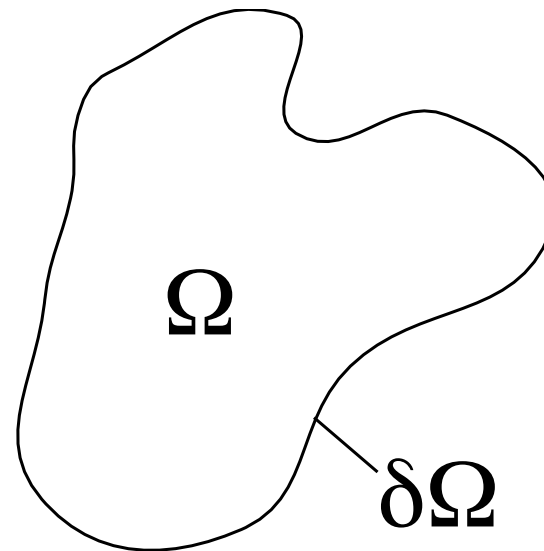
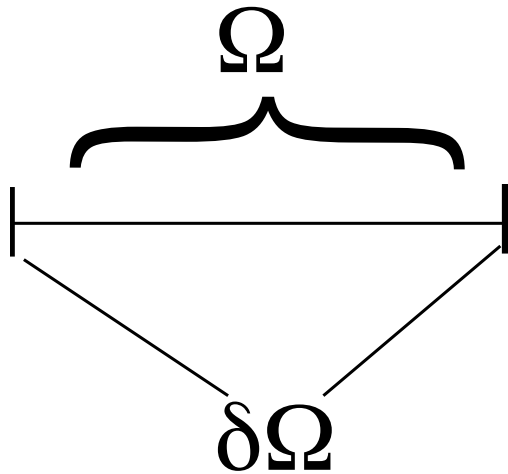
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- Wave equation
- Laplace equation
- Heat equation

# Boundary conditions

For a differential equation to be well posed we need to have appropriate boundary conditions and the same is true for the matrix problem.



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Neumann/Free	$\frac{\partial u}{\partial x}(\partial\Omega) = d$	$\frac{\partial u}{\partial n}(\partial\Omega) = g(\partial\Omega)$
Robin/Mixed	$u(\partial\Omega) + \frac{\partial u}{\partial x}(\partial\Omega) = e$	$u(\partial\Omega) + \frac{\partial u}{\partial n}(\partial\Omega) = h(\partial\Omega)$

# Boundary properties

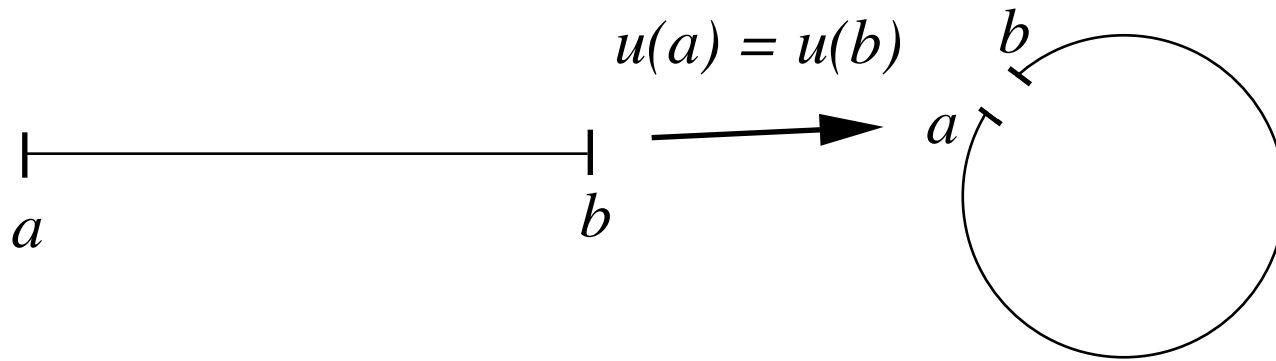
- Different conditions can (and sometimes must) be attached to different parts of the boundary depending on the mathematical properties of the equation.
- For example, if the equation is hyperbolic we must only specify conditions on an inflow boundary.

# Periodic boundary conditions

A useful type of boundary condition is a *periodic* condition

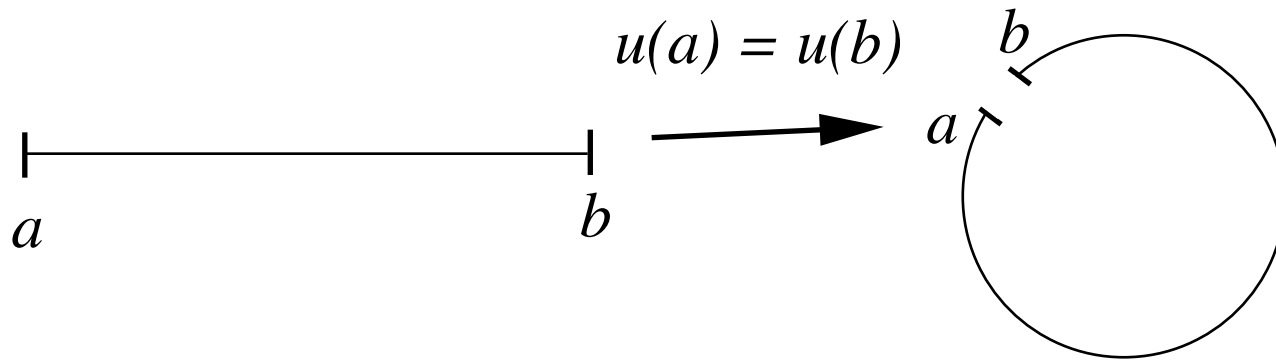
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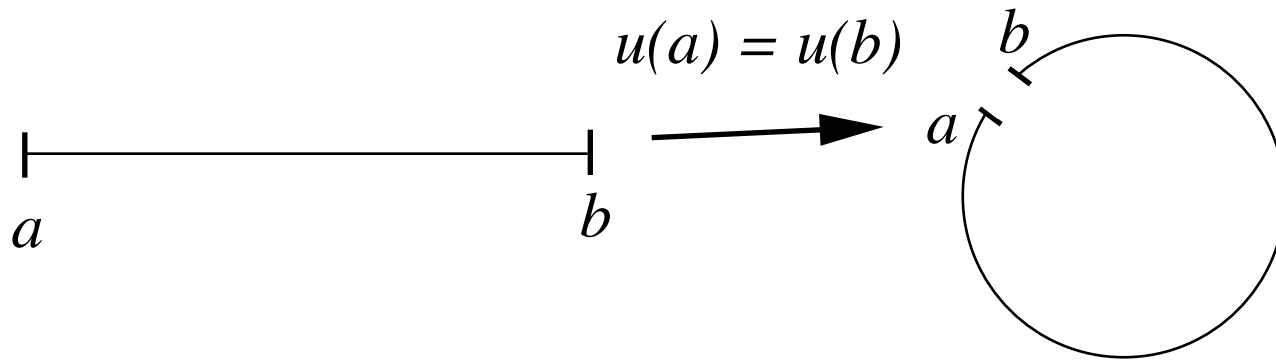
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- A stage of a compressor which is not close to inlet or outlet might also be considered as having periodic boundary conditions.